Lecture 34: P and NP

COSC 311 Algorithms, Fall 2022

Announcement Job Candidate Talk TODAY

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Using Simultaneous Multithreading to Support Real-Time Scheduling

- 4:00 in SCCE A131
- Refreshments at 3:30 in SCCE C209

Homework 6

Posted soon...

...not to be turned in!

• solution posted later this week

Last Time

Two Problems:

- Minimum Vertex Cover (MVC)
- Maximum Indpendent Set (MaxIS)

Polynomial-time reductions between them:

- MVC \leq_P MaxIS
- MaxIS \leq_P MVC

Consequence

• MVC can be solved efficiently ↔ MaxIS can be solved efficiently



Today

- 1. Decision Problems
- 2. The Classes P and NP

A Technicality

Objective. Understand *relationships* between computational problems.

Technical issue. Desired outputs for different problems can be vastly different:

- matching —
- independent set 🔔
- spanning tree 🦟
- ...

Convenience. Focus on decision problems:

• output is "yes"/"no"

MVC vs VC

Minimum Vertex Cover (MVC)

- Input: Graph G
- Output: A vertex cover C of smallest possible size

Vertex Cover (VC)

Input: Graph <u>G</u>, number <u>k</u>

Output:

- "yes" if G has a vertex cover of size k
- "no" otherwise



MaxIS vs IS

Maximum Independent Set (MaxIS)

Input: Graph G

Output: an indpendent set of the largest possible size

Independent Set (IS)

Input: Graph *G*, number *k Output:*

- "yes" if G has an indpendent set of size k
- "no" otherwise

Complexity of Decision Problems

Goal. Classify (decision) problems according to their relative complexities: $Polynomial \rightarrow O(N^{c})$

- which problems can be solved efficiently? for some c
- which problems cannot be solved efficiently?
- which problems can be reduced to other problems?

eq. $\Omega(2^N)$

The Class P

Definition. The class **P** consists of all decision problems that can be solved in polynomial time.

- P = "polynomial time"
- a problem A is in P if there is an algorithm that given any instance X of A
 - the algorithm correctly outputs "yes"/"no"
 - the running time is O(N^c) for some constant c, N = size of input

B= 2 of Tog B Which Problems Are In P? knapsack: can get value of V/ and weight SBE n clements, bro-bn O(M.B) Not polynomial b/c B exp. in logB size of rep. of B. Min. Spanning Tree. Deuisizar Variant: O(mlogn) - Prim is there a spanning free of, weight Lk? Text partition problem from HW.

The Class NP

Verifying Output

Consider IS(G, k):

- "yes" if G has an indpendent set of size k
- "no" if G does not have an indpendent set of size k



NP, Informally

NP = "nondeterministic polynomial time"

Informal Definition. The class NP consists of decision problems whose solution can be *verified* in polynomial time. GK

Setup

- [A is a decision problem, X an instance (input) of A
- If X is a "yes" instance, there should be some way to convince me this is the case
- If X is a "no" instance, there should be no way to convince me X is a "yes" instance

Verifier

Definition. Given a decision problem A, a **verifier** for A is a polynomial time algorithm verify (X, C) that takes as Instance I.S. - Purported input

- an *instance* X of A, and
- eg. G.K • a *certificate C* (size polynomial in size of X)

and returns a value "accept" or "reject," subject to two conditions:

- 1. completeness if X is a "yes" instance, then there exists a certificate C such that verify(X, C) returns "accept"
- 2. soundness if X is a "no" instance, then for every certificate C, verify(X, C) returns "reject"

A Verifier for IS

Consider IS(G, k):

- "yes" if G has an indpendent set of size k
- "no" if G does not have an indpendent set of size k set of vk vert.

What is a verifier for IS?

- what should be the certificate?
- how do we verify a certificate?

for each vertex " in C, check if any of v's neighbors use in C 1 mif so reject offectise

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(purported IS)

NP, Formally

Definition. The class **NP** consists of all decision problems that admit a polynomial time verifier.

NP, Formally

Definition. The class **NP** consists of all decision problems that admit a polynomial time verifier.

• By previous example, IS is in NP

Conceptually NP can be thought of the class of *puzzles*

- a puzzle may be hard to solve
- you can easily verify if you (or someone else) solved the puzzle

P vs NP

Open Question. Is there any problem in <u>NP</u> that is not in <u>P</u>?

Informal statement. Are there problems that are hard to solve, but whose solutions are easy to verify?

• one of deepest mathematical challenges of our time

Activity

Which of the following problems are in NP:

- 1. BipartiteMatching(G, k)
- 2. NoFlow(G, k)
- 3. Generalized Chess(n, C)
- 4. BooleanSatisfiability($\varphi(x_1, x_2, ..., x_n)$)

Bipartite Matching Question. Is BipartiteMatching in NP? Decision: G-does G have a matching of size k? Yes: C: a matching of size k $(v_1, w_1), (v_2, w_2), ..., (v_k, w_k)$ Verify: (1) check these one edges in G (2) chech for no repeated vtx.

More Generally

If a problem A is in P, then A is in NP:

• $P \subseteq NP$

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Why?
  Verify:
      - ignore certificate
       - solve problem
      - return "accept"/"reject"
           depending on if output of
Orig. prob is 'yes'/'ho'
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NoFlow Question. Is NoFlow in NP?

Observation

Even if did not know about the Ford-Fulkerson MaxFlow algorithm, we could still identify NoFlow is in NP.

How?

GeneralizedChess

Question. Is GeneralizedChess in NP?

Chess Remarks

A feature of chess games:

- a game may last exponentially many rounds in the size of the board
- therefore: winning strategy might require exponential time to describe/verify

Fact. GeneralizedChess *requires* exponential time to solve (in *n*).

Consequence. Showing GeneralizedChess is in NP would imply that $P \neq NP$.

Boolean Satisfiability

Question. Is BooleanSatisfiability in NP?

Next Time

• NP Completeness: characterizing the "hardest" problems in NP